

EAST Search History

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
S1	215	382/153.ccls.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/12/20 13:07
S2	1719	382/154.ccls.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/23 17:04
S3	6	382/154.ccls. and kosaka.inv.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/23 14:39
S4	28	("5138667" "5440392" "5531520" "5751843" "5828770" "5832139" "5905806" "5921992" "6013308" "6144761" "6175647" "6222937" "6304680" "6324296" "6363169").PN. OR ("6724930").URPN.	US-PGPUB; USPAT; USOCR	OR	ON	2007/02/23 14:31
S5	899	382/154.ccls. and projection	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/23 18:13
S6	156	382/154.ccls. and projection and (marker fiducial)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/12/17 08:08
S7	128	382/154.ccls. and projection and (marker fiducial) and light\$4	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/23 19:08

S8	383916	((OKADA TAKUSHI SUGIMOTO KOICHI SAKAGAMI MUNEYUKI HATA SEJI).inv.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/23 19:09
S9	735	((OKADA near TAKUSHI) (SUGIMOTO near KOICHI) (SAKAGAMI near MUNEYUKI) (HATA near SEJI)).inv.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/23 19:09
S10	233	((OKADA near TAKUSHI) (SUGIMOTO near KOICHI) (SAKAGAMI near MUNEYUKI) (HATA near SEJI)).inv. and (position)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/24 16:51
S11	243	((OKADA near TAKUSHI) (SUGIMOTO near KOICHI) (SAKAGAMI near MUNEYUKI) (HATA near SEJI)).inv. and (position (three near dimensional))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/23 19:10
S12	25	((OKADA near TAKUSHI) (SUGIMOTO near KOICHI) (SAKAGAMI near MUNEYUKI) (HATA near SEJI)).inv. and (position and (three near dimensional))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/23 19:10
S13	233	((OKADA near TAKUSHI) (SUGIMOTO near KOICHI) (SAKAGAMI near MUNEYUKI) (HATA near SEJI)).inv. and (position)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/24 15:54
S14	2	"20040005092".pn.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/24 16:53
S15	617	382/154.ccls. and projection and light\$4	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/24 16:53

S16	128	382/154.ccls. and projection and (marker fiducial) and light\$4	US-PGRUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/24 16:55
S17	121	382/154.ccls. and projection and (marker fiducial) and light\$4 and ((position location) and (orientat \$4 rotat\$5))	US-PGRUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/24 16:56
S18	6	382/154.ccls. and kosaka.inv.	US-PGRUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/25 19:38
S19	214	382/154.ccls. and robot	US-PGRUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/25 18:59
S20	66	382/154.ccls. and robot with (position location)	US-PGRUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/25 19:00
S21	75	382/154.ccls. and affine near2 transform \$5	US-PGRUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/25 19:38
S22	2	"20030039403".pn.	US-PGRUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/12/17 08:08
S23	2	"5604819".pn.	US-PGRUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/12/17 08:32
S24	2	"6128405".pn.	US-PGRUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/12/17 13:24
S25	2252	382/106,154.ccls.	US-PGRUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/12/17 13:24

S26	387	382/106,154.ccls. and (project\$4) near4 (light illuminat\$4)	US-PGRUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/12/17 13:28
S27	77	382/106,154.ccls. and (project\$4) near4 (light illuminat\$4) and (point fiducial marker) near4 (object) near4 (sensor video camera)	US-PGRUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/12/17 13:37
S28	2	"6574361".pn.	US-PGRUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/12/17 13:38
S29	2	"6046745".pn.	US-PGRUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/12/17 13:38
S30	2	"5699444".pn.	US-PGRUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/12/17 13:38
S31	77	382/106,154.ccls. and (project\$4) near4 (light illuminat\$4) and (point fiducial marker) near4 (object) near4 (sensor video camera)	US-PGRUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/12/17 17:44
S32	122	382/106,154.ccls. and (spot slit) near (light illuminat\$4)	US-PGRUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/12/19 12:35
S33	86	382/106,154.ccls. and (line) near4 (camera video sensor) near4 (object)	US-PGRUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/12/19 12:36
S34	268	382/106,154.ccls. and (distance) near4 (camera video sensor) near4 (object)	US-PGRUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/12/19 16:50

S35	0	382/106,154.ccls. and geometric\$2 near4 (deform\$5) near4 (parameter)	US-PGRUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/12/19 16:52
S36	24	382/106,154.ccls. and geometric\$2 near4 (deform\$5)	US-PGRUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/12/19 17:50
S37	2	"20040080758".pn.	US-PGRUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/12/19 17:50
S38	2	"20040080758".pn.	US-PGRUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/12/19 23:22
S39	2	"20020097906".pn.	US-PGRUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/12/19 23:26
S40	507	382/106,154.ccls. and (calculat\$4 comput\$4 determin\$4) near4 (rotat\$4 orient\$5) and reference	US-PGRUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/12/19 23:28
S41	154	382/106,154.ccls. and (calculat\$4 comput\$4 determin\$4) near4 (rotat\$4 orient\$5) and reference near (shape image object)	US-PGRUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/12/20 01:29
S42	2	"5280542".pn.	US-PGRUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/12/20 02:26
S43	2	"5917940".pn.	US-PGRUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/12/20 02:52
S44	30	liew.xa	US-PGRUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/12/20 02:53

S45	19	382/153.ccls. and camera near4 mount \$4 near4 robot	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/12/20 02:53
S46	87	382/153.ccls. and (position location) near4 information	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/12/20 13:13
S47	46	382/153.ccls. and (position location) near4 information and (camera video sensor) near4 (robot)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/12/20 13:14
S48	33	382/153.ccls. and (position location) near4 information and (camera video sensor) near4 (mount\$5)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/12/20 13:14
S49	367	382/154.ccls. and calibrat\$4 near3 camera	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/07/23 13:10
S50	26	382/154.ccls. and calibrat\$4 near3 (camera and (light slit illuminat\$4))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/07/23 13:22
S51	2	"5280542".pn.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/07/23 17:34

7/ 30/ 2008 3:26:15 PM

C:\Documents and Settings\aliew\My Documents\EAST\Workspaces\10689721.wsp